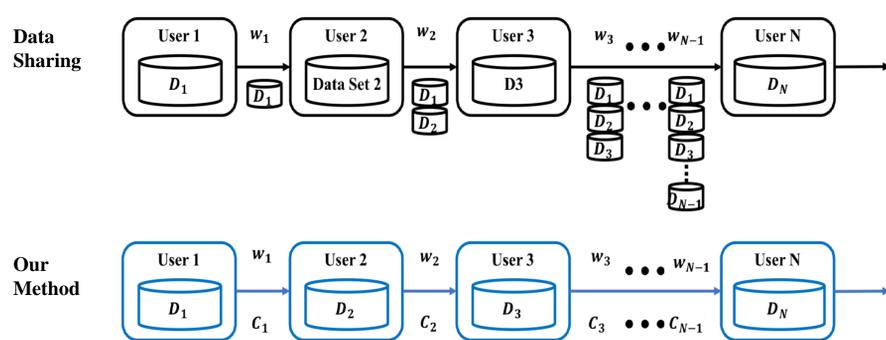


Introduction

- Analytics supported by machine learning models often need to be adapted to changing tactical environments in real time.
- Challenges**
 - When new data samples come, how to update the model without re-training from scratch?
 - How to remove old/bad data samples without re-training from scratch?
 - How to incrementally/decrementally update the model without accessing the previous training data?
 - How to guarantee that the updated model is exactly the same as the model trained from scratch?
- We propose an incremental/decremental learning method for LS-SVM models, which only requires access to the updated data samples, the previous model parameters, and a unique, fixed-size matrix that quantifies the effect of the previous training dataset.

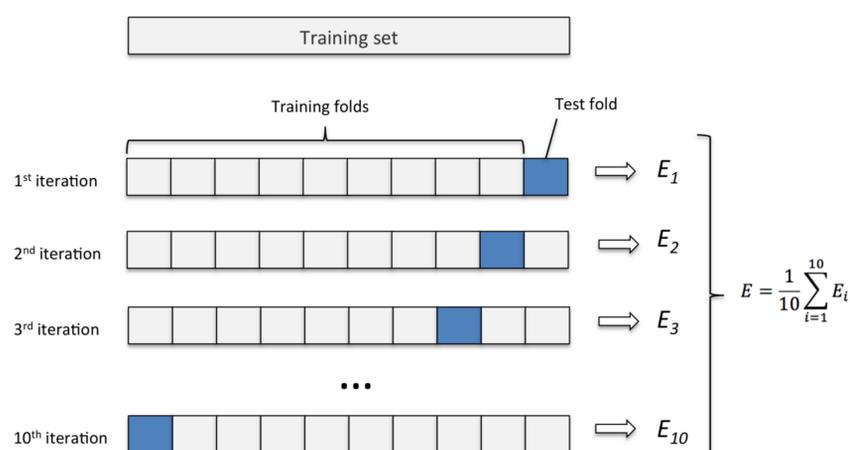
Applications

- Decentralized Learning



Compared to federated learning, our approach only needs one round of local computation at each end user.

- k-fold cross validation



Military & Coalition Relevance

- Models need to be adapted according to dynamically changing tactical situations in real time.
- Data often cannot be shared across coalition boundaries and may be deleted over time.
- Our approach allows coalition member B to update a model provided by coalition member A using coalition B's own local data, for instance.

Approach

LS-SVM: $w^* = \operatorname{argmin}_{w \in \mathbb{R}^J} \rho \|w\|^2 + \sum_{n=1}^N (w^T \vec{\phi}(x_n) - y_n)^2$

$$w^* = \Phi [K + \rho I_N]^{-1} y \quad K = \Phi^T \Phi \quad S = \Phi \Phi^T$$

$$= [\rho I_J + S]^{-1} \Phi y \quad \Phi = \Phi(X) = [\vec{\phi}(x_1), \vec{\phi}(x_2), \dots, \vec{\phi}(x_N)]$$

Incremental and Decremental Learning:

$$w = \Phi [\Phi^T \Phi + \rho I_N]^{-1} y \quad C = \Phi [\Phi^T \Phi + \rho I_N]^{-1} \Phi^T$$

$$w_{\text{new}} = w + (C - I_J) \Phi_c (\rho I - \Phi_c'^T (C - I_J) \Phi_c)^{-1} (\Phi_c'^T w - y_c)$$

$$C_{\text{new}} = C + (C - I_J) \Phi_c (\rho I - \Phi_c'^T (C - I_J) \Phi_c)^{-1} \Phi_c'^T (C - I_J)$$

$$\Phi_c = (\Phi_a, \Phi_r) \quad \Phi_c' = (\Phi_a, -\Phi_r) \quad y_c = (y_a, -y_r)$$

(X_a, y_a) : New training data (X_r, y_r) : Data removed from model

$\vec{\phi}(x_1)$: Arbitrary kernel function applied to data sample x_1

Results

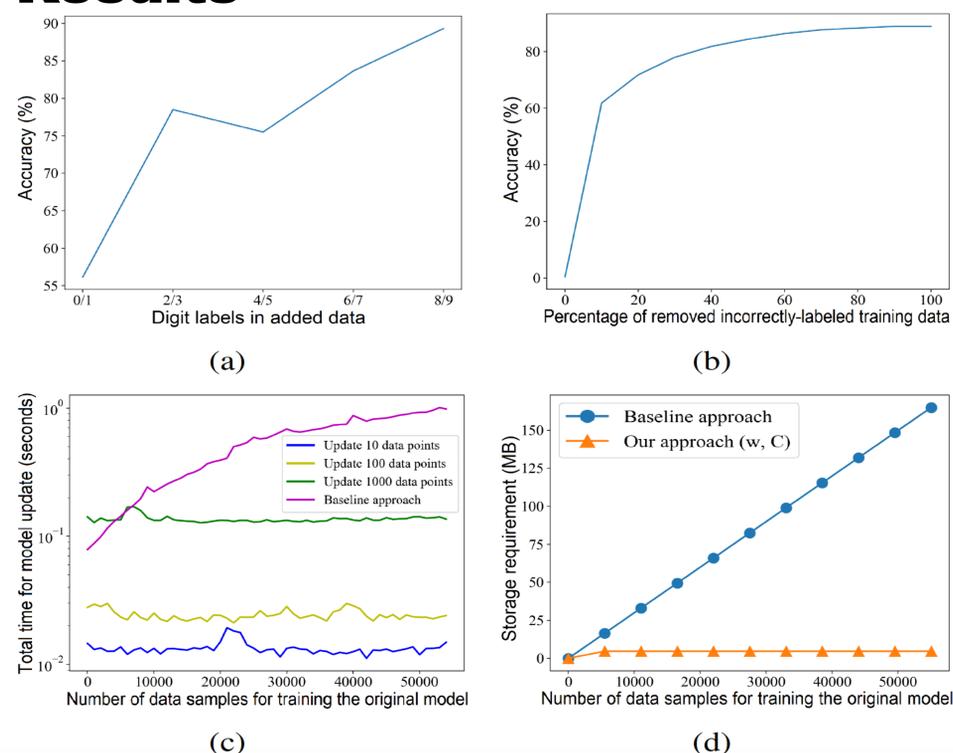


Fig. 1. Experimentation results: (a) model accuracy when incrementally adding each group of data; (b) model accuracy after removing different percentages of incorrectly labeled training data; (c) total time for model update/retraining; (d) storage requirement

Summary

- By leveraging a unique auxiliary matrix, our proposed approach can update LS-SVM models incrementally and decrementally without accessing previous training data.
- Our approach can significantly reduce the storage requirement of model updating, preserve the privacy of unchanged training samples without loss of model accuracy, and enhance the computational efficiency.
- Experiments on real-world image dataset validate the effectiveness of our proposed method.

Publications

- W.-H. Lee, B. J. Ko, S. Wang, C. Liu, K. K. Leung, "Exact incremental and decremental learning for LS-SVM," accepted at the 26th IEEE International Conference on Image Processing (ICIP), Sept. 2019.