

Data Transfer for Distributed Analytics with Latency Constraints



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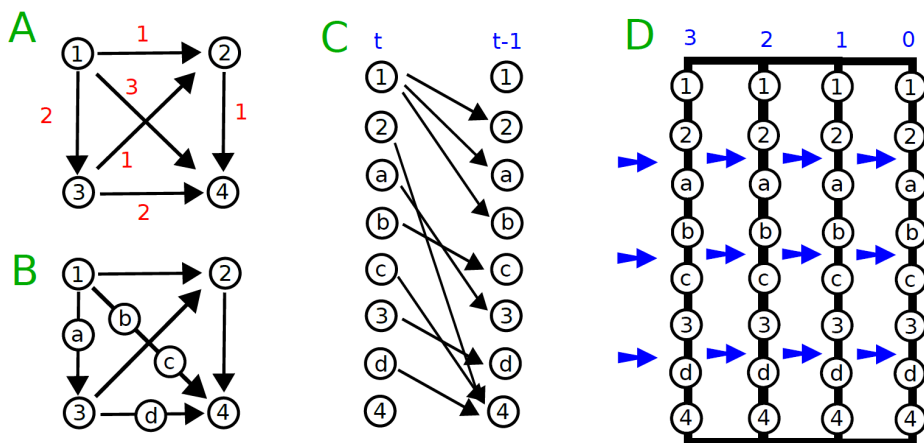
Problem Description

- Directed graph $G = (V, E)$
 - The vertices of the graph represent routers and the edges of the graph represent (direct) communication pipelines
- For every directed edge $(v, w) \in E$, we have an associated bandwidth, $\beta(v, w) \in \mathbb{R}^+$, and transmission latency, $\lambda(v, w) \in \mathbb{R}^+$

The problem: We have Δ bits of data stored at a “source” vertex, $\perp \in V$, which need to be transferred to a “sink” vertex, $\top \in V$. We need to compute how to route the data so that this data-transfer **takes the minimum possible time**.

Frame Graph

Graph Definition



- A: The original graph G with latencies in red
 B: Intermediate graph
 C: Frame t of the frame graph
 D: The first three frames of the frame graph (blue arrows represent the edges in diagram C)

Dynamic Flow

A “dynamic flow”, F , on the frame graph H is a function $F: D \rightarrow \mathbb{R}^+$ such that $\sum_{u \in U: (u,v) \in D} F(u, v) = \sum_{w \in U: (v,w) \in D} F(v, w)$ for all $v \in U$ with $v \notin \cup_{t \in \mathbb{N}} \{\perp(t), \top(t)\}$.

Constructing a Dynamic Flow

For $i \in \mathbb{N}$, at the start of round i , we have a dynamic flow F_i , initialised such that $F_1(e) = 0$ for all $e \in D$. On round i we do the following:

- Let s be equal to the minimum t such that that there exists an F_i -augmenting path from $\perp(t)$ to $\top(1)$. Let P be such a path. If there is no such F_i -augmenting path then quit the algorithm with F_i being the required dynamic flow.
- Set $F' \leftarrow F_i \oplus P$
- Write P as a sequence $\{x_1, x_2, x_3, \dots, x_l\}$, of vertices in U
- For all $i < l$:
 - If $\psi_P(x_i) = 1$ set $e \leftarrow (x_i, x_{i+1})$. Else set $e \leftarrow (x_{i+1}, x_i)$
 - Let r be such that $e \in Z_r$
 - For all $t > r$ set $F'(\uparrow_t(e)) \leftarrow F'(e)$
- Set $F_{i+1} \leftarrow F'$

Implicit Construction

To reduce computational complexity

Definition: Given a path $P := \{v_1, v_2, \dots, v_l\}$ in G' , its “effective length” is defined equal to

$$\sum_{i < l: \psi_P(v_i) = 1} \lambda(v_i, v_{i+1}) - \sum_{i < l: \psi_P(v_i) = -1} \lambda(v_{i+1}, v_i)$$

Algorithm: On round i the algorithm does the following:

- Let P be an f_i -augmenting path in G' from \perp to \top of minimum effective length. If there is no such path then the algorithm terminates with the required scheduling.
- Set $f_{i+1} \leftarrow f_i \oplus P$
- Let $(\perp = v_1, v_2, \dots, v_l = \top) := P$
- For all $i < l$:
 - If $\psi_P(v_i) = 1$ let $e \leftarrow (v_i, v_{i+1})$; else let $e \leftarrow (v_{i+1}, v_i)$
 - Let ζ be the effective length of the path $(v_i, v_{i+1}, v_{i+2}, \dots, v_l = \top)$
 - $\mu(e) \leftarrow \mu(e) + 1$
 - $\delta_e(\mu(e)) \leftarrow \zeta$
 - $\epsilon_e(\mu(e)) \leftarrow f_{i+1}(e)$